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ML Emulation of High Resolution Inundation Maps

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Introduction

- Often need vast numbers of simulations (10000+)
- Inundation is by far the most expensive part of the calculation.
- Offshore time-series are relatively cheap to calculate.
- Is it possible to replace the simulation of the inundation by a statistical emulator?

(Full numerical simulation using nested grid)
Introduction

- Often need vast numbers of simulations (10000+)
- Inundation is by far the most expensive part of the calculation.
- Offshore time-series are relatively cheap to calculate.
- Is it possible to replace the simulation of the inundation by a statistical emulator?

(Predict inundation using ML)

(Calculate offshore time-series in numerical simulation)
For such a procedure to be feasible we would require:

- Possible with a relatively small training set.
- An acceptable level of accuracy in the predictions.
- Good performance for low-probability, extreme events.
- Significant improvement in time-to-solution relative to the full numerical simulation.
Dataset from the ChEESE-1P Project

Probabilistic Tsunami Hazard Analysis performed for Eastern Sicily (Catania and Siracusa):

- Around 42,000 initial simulations for these sites.
- 10m resolution inundation grids for coastal regions of interest.
- Offshore time-series saved for all simulations.

Probabilistic Tsunami Hazard Analysis: High Performance Computing for Massive Scale Inundation Simulations

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Before we try to reproduce inundation maps, we test whether or not we can reproduce statistical metrics of the maps.

- A metric of regional inundation is the total area subject to inundation in the Catania region.
- The vast majority of the scenarios inundate less than 3 km$^2$.
- A machine learning model able to predict more severe inundation scenarios will need an appropriate training set.
Stage 1 validation: Predicting Inundation Statistics

Before we try to reproduce inundation maps, we test whether or not we can reproduce statistical metrics of the maps.

- The Maximum Inundation Height (MIH) is the metric that is of interest – ultimately at every location on the map.
- Here we display the maximum MIH achieved at any location on the grid in a single simulation.

(The highest MIH values are often very local.)

Histogram of MIH (Catania)

(MIH from numerical simulations)
Stage 1 validation: Predicting Inundation Statistics

First test is to reproduce the total inundation area (scalar value) from offshore time-series using a CNN. Results are promising – it looks like we may underestimate the inundation in the more severe cases.
Stage 1 validation: Predicting Inundation Statistics

(with randomly selected training set)

Looking at the statistics of the modelled and predicted inundation areas, we may be doing better than the scatterplot suggests.

However, we clearly overestimate the inundation for some of the smallest – and underestimate for some of the largest.
Stage 1 validation: Predicting Inundation Statistics
(with randomly selected training set)

The performance in estimating the (global) maximum inundation height (MIH) is similar. The spread appears greater than for the inundated area.
Towards predicting inundation maps

Our simple model (which worked quite well for the global scalar quantities) struggles to model the maximum inundation heights at individual sites.

• Performance is especially poor for inland points that are rarely inundated.
• We do not exploit the joint distribution of the targets at the different locations.
So – we need to rethink this!

- If we pick training sets randomly we will likely need an unacceptably high number of training scenarios.
- Our inundation parameter space is very large (several million pixels) – or is it? (It is always the lowest-lying locations, or those closest to the shore that are inundated the most.)
  - There is likely significant correlation between one inundation map and the next. Can we exploit this?
  - Can we cover our parameter space with far fewer parameters?
(1) Choosing an appropriate training set

However, it is the statistics of inundation we want to predict – we do not have access to these values when choosing our training set.

- To the right is the distribution of maximum offshore wave amplitudes (at a single tide-gauge offshore Catania).
- Displayed is a possible way of selecting a training set which covers both the more typical (low to moderate inundation) and the extreme cases (high inundation).
(2) Dimensionality of our inundation maps

Autoencoders

https://en.wikipedia.org/wiki/Autoencoder
(2) Dimensionality of our inundation maps

Simulated inundation map

Convolutional encoder

Reconstructed inundation map

Large dimension

Low dimension

Large dimension

https://en.wikipedia.org/wiki/Autoencoder
15 - GC11-Solid
Earth
We test the viability of predicting the inundation using an auto-encoder.

We want to investigate the size of the latent space needed to be able to accurately reconstruct inundation patterns.

We want to investigate the size and selection of the training sets on the ability to predict an inundation pattern from offshore time-series.

We be considering the entire grid of points but for ease of display will consider a distinct set of points along the coast at Catania.

Some locations are right at the shoreline and are essentially always inundated.

Some locations are further inland and at some height. They are more seldom inundated.
The inundation at the locations further inland is underestimated more often than the inundation at the near-shore locations.
Results: Example 1 – Large inundation (highest error)

Largest inundation ($l^1$) on test set (also largest error). 286 training samples.
Results: Example 2 – Large inundation

Second largest inundation ($l^1$) on test set. 286 training samples.
Results: Example 3 – Error low but spatial pattern not very accurately reproduced.

95% quantile ($l^1$) on test set. 286 training samples.
Conclusions

• A convolutional network acting on offshore time-series is able to predict tsunami inundation statistics and maps.

• Predictions for the coast of Eastern Sicily (Bay of Catania) were satisfactory with training sets with several hundred scenarios. (As opposed to many thousands needed for PTHA or PTF)

• An Autoencoder allows us to represent the high-dimensional inundation maps with a far lower dimensional latent space. (Significant work remaining on determining optimal dimensions)

• Training set must have sufficient size (to avoid overfitting) and be sufficiently diverse (to cover higher inundations).
Thank you!